Synchronization Data Structures

// Task: Implement a queue with a maximum capacity.

// PART 1

// Basic Queue: no synchronization

typedef struct queueelem {
    queuedata_t data;
    struct queueelem *next;
} queueelem_t;

typedef struct queue {
    int capacity;
    int size;
    queueelem_t *head;
    queueelem_t *tail;
} queue_t;

// A queue is a first-in, first-out (FIFO) list of data items, with length
// at most 'q->capacity'. We store those items as a singly linked list.
// We add elements at the 'tail' end of the queue, and remove elements from
// the 'head' end. After calls to 'queue_enq(q, 1)', 'queue_enq(q, 2)',
// and 'queue_enq(q, 3)', the queue 'q' might look like this:

// `q'
// +--------+
// | cap. 8 |
// | size 3 | queueelem_t's
// |       +-------+-------+-------+
// | head >>>>>>| 1 -----| 2 -----| 3 XX|
// |          +-------+-------+-------+
// | tail >>>>>^ 
// +--------+ \-------------------/

// Then, after calling 'queue_deq(q)' (which would return 1):

// `q'
// +--------+
// | cap. 8 |
// | size 2 |
// |       +-------+-------+
// | head ---------------->>>| 2 -----| 3 XX|
// |                      +-------+-------+
// | tail >>>>>^ 
// +--------+ \-------------------/
// Then, after calling 'queue_enq(q, 4)'
//
// 'q'
// +--------+
// | cap. 8 |
// | size 3 |
// |       +------- +------- +-------+
// | head ----------> 2 ------| 3 ------| 4 X stal
// |       +------- +------- +-------+
// | tail -----
// +--------+ \\

// Some invariants:
// * q->size >= 0
// * q->size <= q->capacity
// * If q->tail == NULL, then q->head == NULL and q->size == 0
// * If q->head == NULL, then q->tail == NULL and q->size == 0
// * If q->tail != NULL, then q->tail->next == NULL

// Create a new queue
queue_t *
queue_init(int capacity)
{
    queue_t *q = (queue_t *) malloc(sizeof(queue_t));
    q->head = q->tail = NULL;
    q->size = 0;
    q->capacity = capacity;
    return q;
}

// Enqueue 'data'
void
queue_enq(queue_t *q, queuedata_t data)
{
    queueelem_t *qe = (queueelem_t *) malloc(sizeof(queueelem_t));
    assert(q->size < q->capacity);

    qe->data = data;
    qe->next = NULL;
    if (q->tail)
    q->tail->next = qe;
    else
    q->head = qe;
    q->tail = qe;
    q->size++;
// Dequeue and return
queuedata_t
queue_deq(queue_t *q)
{
    queueelem_t *qe;
    queuedata_t data;
    assert(q->size > 0);

    qe = q->head;
    q->head = qe->next;
    if (q->head == NULL)
        q->tail = NULL;
    q->size--;

    data = qe->data;
    free((void *) qe);
    return data;
}
// PART 2

// Synchronized Queue: add spin locks to prevent race conditions

typedef struct queue {
    // ...
    spinlock_t lock;
} queue_t;

queue_t *
queue_init(int capacity)
{
    // ...
    spinlock_init(&q->lock);
    return q;
}

void
queue_enq(queue_t *q, queuedata_t data)
{
    queueelem_t *qe = (queueelem_t *) malloc(sizeof(queueelem_t));
    qe->data = data;

    // Spin until there's room on the queue
    while (1) {
        spin_lock(&q->lock);
        if (q->size < q->capacity)
            break;
        spin_unlock(&q->lock);
    }

    qe->data = data;
    qe->next = NULL;
    if (q->tail)
        q->tail->next = qe;
    else
        q->head = qe;
    q->tail = qe;
    q->size++;

    spin_unlock(&q->lock);
}
queueelem_t *qe = NULL;
queuedata_t data;

// Spin until there's something on the queue
while (1) {
spin_lock(&q->lock);
if (q->head != NULL)
    break;
spin_unlock(&q->lock);
}

qe = q->head;
q->head = qe->next;
if (q->head == NULL)
    q->tail = NULL;
q->size--;

// Done with shared variables, so release lock
spin_unlock(&q->lock);
data = qe->data;
free((void *) qe);
return data;
// PART 3

// Simple implementation of sleep() and wakeup(), to demonstrate the
// sleep/wakeup race condition

void
sleep(process_t *p, waitqueue_t *wq)
{
    p->waiting = wq;
    p->wait_next = wq->next;
    wq->next = p;
    p->blocked = 1;
    yield(); // Will not return until wq is woken up
}

void
wakeup(waitqueue_t *wq)
{
    process_t *p;
    while ((p = wq->next)) {
        wq->next = p->wait_next;
        p->waiting = 0;
        p->wait_next = NULL;
        p->blocked = 0;
    }
}
// PART 4

// Queue with Condition Variables

// 'q->nonempty' represents the condition 'queue q is not empty'.
// 'q->nonfull' represents the condition 'queue q is not full'.

typedef struct queue {
    // ...
    condition_t nonempty;
    condition_t nonfull;
} queue_t;

void
queue_enq(queue_t *q, queuedata_t data) {
    queueelem_t *qe = (queueelem_t *) malloc(sizeof(queueelem_t));
    qe->data = data;

    spin_lock(&q->lock);
    while (q->size == q->capacity)
        condition_wait(&q->nonfull, &q->lock);
    qe->data = data;
    qe->next = NULL;
    if (q->tail)
        q->tail->next = qe;
    else
        q->head = qe;
    q->tail = qe;
    q->size++;
    spin_unlock(&q->lock);
    // Q: Why is it OK to signal the condition outside the spin lock?
    condition_signal(&q->nonempty);
}
queue_t
queue_deq(queue_t *q)
{
    queueelem_t *qe = NULL;
    queuedata_t data;

    spin_lock(&q->lock);
    while (q->size == 0)
    {
        condition_wait(&q->nonempty, &q->lock);

        qe = q->head;
        q->head = qe->next;
        if (q->head == NULL)
            q->tail = NULL;
        q->size--;

        spin_unlock(&q->lock);
        data = qe->data;
        free((void *) qe);
        condition_signal(&q->nonfull);
    }
    return data;
}
// PART 5

// Lock-Free Queue with single writer and single reader

typedef struct queue {
    int capacity;
    queuedata_t *queue;
    int head;
    int tail;
} queue_t;

// Locks and other synchronization objects (such as condition variables)
// are very powerful, but they're not the only way to synchronize!
// A "lock-free" data structure is safe to use concurrently, but totally
// avoids locking. Some advantages (+) and disadvantages (-):
// (+) Lock-free data structures often perform better, because there's no
//     locking overhead.
// (+) Lock-free data structures avoid concurrency bugs by design.
// (-) Lock-free data structures can be more complex than conventional,
//     locking-based data structures.

// This code implements a lock-free FIFO queue, under the single-reader/
// single/reader assumption. That is, we assume that at most one process will
// call queue_enq at a time, and similarly for queue_deq; but processes might
// call queue_enq and queue_deq simultaneously, so we still have to be careful!

// The basic idea is simple: we divide up the data structure's state so that
// every member has *exactly one writer*. Then there's no need for locking,
// because there's no field-level concurrency!

// For example, look at the code for the lock-protected queue. Notice that
// the 'enq' method mostly references 'q->tail', and the 'deq' method
// mostly references 'q->head'. This is just like we'd expect: adding data
// to the queue affects the tail, and removing data affects the head. So
// in the lock-free queue, we just make sure that 'enq' NEVER writes to
// 'q->head', and that 'deq' NEVER writes to 'q->tail'! But how to do
// this? We can't use linked lists any longer, since they would require
// 'enq' to write to 'q->head' occasionally. Instead, we implement the
// queue as an array, and 'q->head' and 'q->tail' as indexes into the
// array. That gives us everything we want.

// All this is clearer in some examples. Here's an empty lock-free queue
// with capacity of 8. Note that there are nine elements in the array;
// this lets us distinguish between an empty queue and a full queue (you'll
// see how).
//
// +--------+ +----+----+----+----+----+----+----+----+----+
// | cap. 8 | | | | | | | | | | |
// | | +----+----+----+----+----+----+----+----+----+
// | head 0 |------ˆ ˆ
// | tail 0 |---------+
// +--------+
Note that 'q->head == q->tail' means the queue is empty.

After calling 'queue_enq(q, 1)', the queue shifts to this state:

```
+--------+ +----+----+----+----+----+----+----+----+----+
| cap. 8 | | 1 | | | | | | | |
| | +----+----+----+----+----+----+----+----+----+
| head 0 |-------ˆ ˆ
tail 1 |-----------+
+--------+
```

After calling 'queue_enq(q, 2) :

```
+--------+ +----+----+----+----+----+----+----+----+----+
| cap. 8 | | 1 | 2 | | | | | | |
| | +----+----+----+----+----+----+----+----+----+
| head 0 |-------ˆ ˆ
tail 2 |-----------------+
+--------+
```

Then after calling 'queue_deq(q)', which returns 1:

```
+--------+ +----+----+----+----+----+----+----+----+----+
| cap. 8 | | | 2 | | | | | | |
| | +----+----+----+----+----+----+----+----+----+
| head 1 |------------ˆ ˆ
tail 2 |-----------------+
+--------+
```

Note that the enq operation only writes to (1) the 'tail' member and (2) the previously-blank queue entries. The deq operation, by contrast, writes to (1) the 'head' member and (2) the NON-blank queue entries.

The different operations "never write to the same part of the data structure"! Thus, lock-freedom.

If we add and remove a bunch more items, we might reach a state like this:

```
+--------+ +----+----+----+----+----+----+----+----+----+
| cap. 8 | | 10 | | 6 | 7 | 8 | 9 |
| | +----+----+----+----+----+----+----+----+----+
| head 5 |---------------------------
tail 1 |-----------------+
+--------+
```

This queue contains the elements 6, 7, 8, 9, and 10, in that order.

Notice that the tail pointer has "wrapped around"; this is why the queue is called circular.
// If we add 3 more items to the queue, it will become full:
//
// +--------+ +----+----+----+----+----+----+----+----+----+
// | cap. 8 | | 10 | 11 | 12 | 13 | | 6 | 7 | 8 | 9 |
// | | +----+----+----+----+----+----+----+----+----+
// | head 5 |-------------------------------^
// | tail 4 |---------------------------^
// +--------+

// Notice that a "full" queue has one blank slot. We need that blank slot
// to distinguish the "full" case from the "empty" case. Specifically:
// The queue is empty when head == tail;
// The queue is full when (head + capacity) % (capacity + 1) == tail
// --- that is, when there's one slot left.

// Lock-free data structures are a particularly powerful form of advanced
// OS data structure design. It's worth your time to think about this
// code for a while. Note that, although the code may appear unfamiliar to
// you, it is *shorter* than any of the locking designs. Feel free to ask
// questions!

// A question for you: How would you make this data structure safe for
// multiple concurrent readers and/or writers?

queue_t *
queue_init(int capacity)
{
    queue_t *q = (queue_t *) malloc(sizeof(queue_t));
    q->queue = (queuedata_t *) malloc(sizeof(queuedata_t) * (capacity + 1));
    q->head = 0;
    q->tail = 0;
    q->capacity = capacity;
    return q;
}

void
queue_enq(queue_t *q, queuedata_t data)
{
    // This is lock-free, but not *wait*-free, since we wait for a slot if the
    // queue is full. But that can't be avoided unless we implement a
    // non-blocking enq.
    while (((q->tail + 1) % (q->capacity + 1) == q->head)
        yield();
    q->queue[q->tail] = data;
    q->tail = (q->tail + 1) % (q->capacity + 1);
}
queuedata_t
queue_deq(queue_t *q)
{
    queuedata_t data;

    while (q->head == q->tail)
        yield();

    data = q->queue[q->head];
    q->head = (q->head + 1) % (q->capacity + 1);
    return data;
}